Order form
(specimen suitable for photocopying)

Controllers
For "light hoisting" applications, type **XKB E**
Controllers XKB E with variable and modifiable schemes, factory assembled

Customer		Schneider Electric Industries			
Company	Customer's reference	Sales office - Subsid. - Plant	Editor	Geographical zone	Order N°

Reference (use the grid for composing the reference of a controller on page 12)

		Model	Contacts	Handle	Lever movement AB CD	Potentiometer adaptation
Number of identical units	**XKB**	**E** ☐	☐	☐	☐ ☐	☐

| For Schneider Electric Industries use only											
Order N°	Item N°	**XKB**	MOD ☐	ETI ☐	POI ☐	GLV ☐	CTS ☐	MAB ☐	MCD ☐	PAB ☐	PCD ☐

Lever gate
In accordance with the half-gates available, sketch and crosshatch the lever's field of movement on the scheme grids below.
In the absence of this information, the controller will be supplied with a "universal" gate.

Potentiometer adaptation
Cross ☒ the required position on the schemes below.

| **On movement AB** | Type/size: |
	Value:
On movement CD	Type/size:
	Value:

Legend

Without legend	☐
With blank legend, **XKB Y1**	☐
With "traverse-slew" symbols, **XKB Y2**	☐
With "hoist-long travel" symbols, **XKB Y3**	☐
With specific engraved text, **XKB Y1001** (clearly state the text on the scheme below) Left-hand operated unit	☐
Right-hand operated unit	☐

⚠ If the scheme is not defined, all **XKB E** controllers will be supplied with the standard scheme as used for XKB A.

Scheme 1: 4 contacts per movement (viewed from above)
Orientation locater
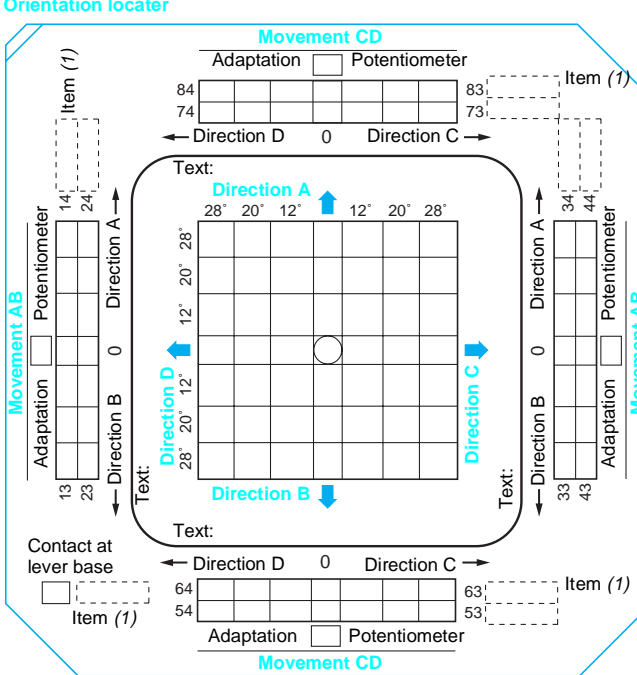
Scheme 2: 4 contacts + 1 zero (centre) position contact per movement (viewed from above)
Orientation locater
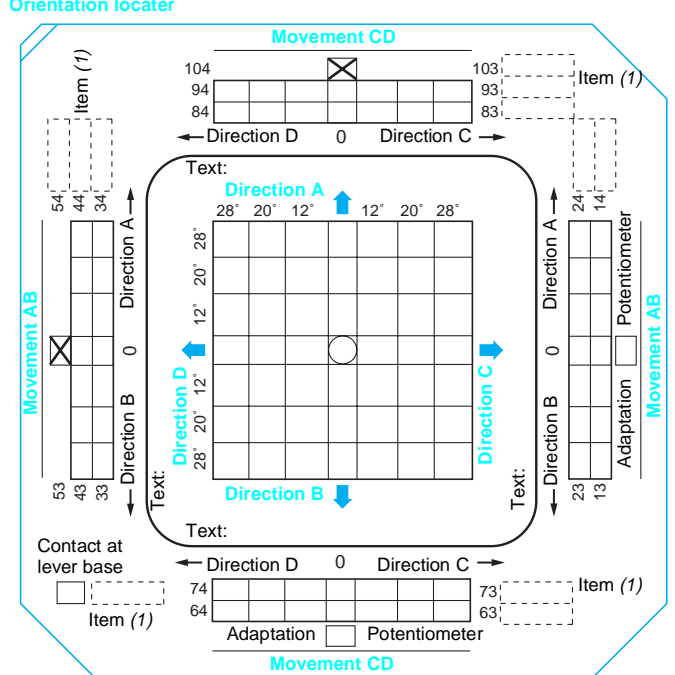
(1) Reserved for contact identification in the automation system scheme. It is not possible to mark it on the controller.
Spring return operation: only 1 contact can be used with spring return at each notch.

⊕ **Telemecanique**