## Order form

(specimen suitable for photocopying)

## **Controllers**

For "light hoisting" applications, type **XKB E**Controllers XKB E with variable and modifiable schemes, factory assembled

_									
Customer	1.			ler Electri					l <b>a</b>
Company	Custom	ner's reference	Sales offi	ice - Subsi	d Plant	Editor	Geogra	aphical zone	Order N°
Reference (use the grid for composing the reference of a controller on page 12)									
Reference (use ti	ne gria for cor	nposing the refere	Model	Contacts		Lever mov	omont.	Potentiomete	r adaptation
			Model	Contacts	папине	AB	CD	Potentiomete	гацаріаноп
Number of identical units	6	ХКВ	E						
For Schneider Electric	Industries use	only							
Order N	III IN		MOD	ETI	POI	GLV	CTS	MAB MC	D PAB PCD
		ХКВ							
Lever gate			Potention	neter adap	tation				
In accordance with the ha	alf-gates available	e, sketch and	Cross <b>⊠</b> th	ne required		the schem	es below.		
crosshatch the lever's field of movement on the scheme grids below.			On moven	nent AB		Type/size:			
In the absence of this information, the controller will be			0			Value:			
supplied with a "universal" gate.			On moven	nent CD		Type/size: Value:			
Legend						value.			
Without legend									
With blank lagand VVD									
With blank legend, XKB Y1									
With "traverse-slew" symbols, XKB Y2									
With "hoist-long travel" symbols, XKB Y3									
With specific engraved text, XKB Y1001									
(clearly state the text on the scheme below)  Left-hand operated unit									
△ If the scheme is not defined, all <b>XKB E</b> controllers will be supplied with the standard scheme									
Right-hand operated unit as used for XKB A.									
Scheme 1: 4 contacts p	er movement (vie	ewed from above)		Scher	ne 2: 4 cor	ntacts + 1 ze	ero (centre	e) position conta	act per movement (viewe
from above)									
Orientation locater Orientation locater									
_ =	Movement Adaptation	Potentiometer			5		Movem	nent CD	
(1) Rem (1) 84 74	/ taptation	83	ltem (1)		Item (1)	104 94		$\times$	103 93 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
<u>⊕</u> 74		73	¦ 	,	<u>\$</u>	84			83
<b>←</b> Di	rection D 0	Direction C →				→ Direc	tion D	0 Direction	C
Text					/	Text:	antinu A		
P 2 2 4 5	Direction A	12° 20° 28°	4 4 3 <b>10</b>	54	4 8		ection A 20° 12°	12° 20° 28	4 4 4
Potentiometer Potentiometer Direction A-			Direction A –		Direction A	28°			Direction A.
otentiome Otertiome Direction					actic	20°			- ctio
				Movement AB	ШΙ	12°			
	++		$^{\circ}$		$\square$			4	tion C to B 0 or ation C to Company
on L		5	g light		a	on [			Lion B B
Adaptation Adaptation Fection B Direction I 28° 20° 12		Direction	rection B	-   -   -   -	l ig l	20°			Direction Prection B Adaptation
Adapta Adapta  Adapta  23 Ext:  Ext:  28 20 28 20		<u> </u>	Ag Bell		43 33 — Direction	58° = 1			Adá P
	Direction B	Jext	33 Adapta	53	25 E I	Dir	ection B	<u> </u>	Direction  Text:
Text	•	5)	▼		* (	− \ Text:		<b>▼</b>	~ <b>/</b>
Contact at	rection D 0	Direction C			tact at	Direc	tion D	0 Direction	<u>·</u>
lever base 64	100001111111111111111111111111111111111	63	Item (1)	leve	er base	74	1011 D	- 5460001	73; Item (1)
Item (1) 54 L		53	·¦ /	/ \	Item (1)	64			63
	<u> </u>	Potentiometer			` '	Ad	aptation [	Potentiome	eter /
	Movement	CD					Movem	IENT CD	

<sup>(1)</sup> Reserved for contact identification in the automation system scheme. It is not possible to mark it on the controller. Spring return operation: only 1 contact can be used with spring return at each notch.