



Main

Range of product	Altivar 71
Product or component type	Variable speed drive
Product specific application	Complex, high-power machines
Component name	ATV71
Motor power kW	22 kW at 380...480 V 3 phases
Motor power hp	30 hp at 380...480 V 3 phases
Motor cable length	<= 100 m <= 200 m
Power supply voltage	380...480 V (- 15...10 %)
Network number of phases	3 phases
Line current	42 A for 480 V 3 phases 22 kW / 30 hp 50 A for 380 V 3 phases 22 kW / 30 hp
EMC filter	Integrated
Assembly style	With heat sink
Variant	Control synchronous motors with speed feedback
Apparent power	32.9 kVA at 380 V 3 phases 22 kW / 30 hp
Prospective line I _{sc}	<= 22 kA, 3 phases
Nominal output current	40 A at 4 kHz 460 V 3 phases 22 kW / 30 hp 48 A at 4 kHz 380 V 3 phases 22 kW / 30 hp
Maximum transient current	72 A for 60 s 3 phases 22 kW / 30 hp 79.2 A for 2 s 3 phases 22 kW / 30 hp
Output frequency	0.1...599 Hz
Nominal switching frequency	4 kHz
Switching frequency	1...16 kHz adjustable 4...16 kHz with derating factor
Asynchronous motor control profile	ENA (Energy adaptation) system for unbalanced loads Flux vector control (FVC) with sensor (current vector) Sensorless flux vector control (SFVC) (voltage or current vector) Voltage/frequency ratio (2 or 5 points)
Type of polarization	No impedance for Modbus

Complementary

Product destination	Asynchronous motors Synchronous motors
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Power supply voltage limits	323...528 V
Power supply frequency	50...60 Hz (- 5...5 %)
Power supply frequency limits	47.5...63 Hz
Speed range	1...100 for asynchronous motor in open-loop mode, without speed feedback 1...50 for synchronous motor in open-loop mode, without speed feedback 1...1000 for asynchronous motor in closed-loop mode with encoder feedback
Speed accuracy	+/- 0.01 % of nominal speed for 0.2 Tn to Tn torque variation in closed-loop mode with encoder feedback +/- 10 % of nominal slip for 0.2 Tn to Tn torque variation without speed feedback
Torque accuracy	+/- 15 % in open-loop mode, without speed feedback +/- 5 % in closed-loop mode with encoder feedback
Transient overtorque	220 % of nominal motor torque +/- 10 % for 2 s 170 % of nominal motor torque +/- 10 % for 60 s every 10 minutes
Braking torque	<= 150 % with braking or hoist resistor 30 % without braking resistor
Synchronous motor control profile	Vector control without speed feedback
Regulation loop	Adjustable PI regulator
Motor slip compensation	Adjustable Automatic whatever the load Not available in voltage/frequency ratio (2 or 5 points) Suppressable
Diagnostic	1 LED red presence of drive voltage
Output voltage	<= power supply voltage
Insulation	Electrical between power and control
Type of cable for mounting in an enclosure	With a NEMA Type1 kit : 3-strand UL 508 cable at 40 °C, copper 75 °C PVC With an IP21 or an IP31 kit : 3-strand IEC cable at 40 °C, copper 70 °C PVC Without mounting kit : 1-strand IEC cable at 45 °C, copper 70 °C PVC Without mounting kit : 1-strand IEC cable at 45 °C, copper 90 °C XLPE/EPR
Electrical connection	A11-/A11+, A12, AO1, R1A, R1B, R1C, R2A, R2B, L1...L16, PWR terminal 2.5 mm ² / AWG 14 L1/R, L2/S, L3/T, U/T1, V/T2, W/T3, PC/-, PO, PA/+, PA, PB terminal 50 mm ² / AWG 1/0
Tightening torque	L1/R, L2/S, L3/T, U/T1, V/T2, W/T3, PC/-, PO, PA/+, PA, PB 12 N.m / 102.2 lb.in A11-/A11+, A12, AO1, R1A, R1B, R1C, R2A, R2B, L1...L16, PWR 0.6 N.m
Supply	Internal supply for reference potentiometer (1 to 10 kOhm), 10.5 V DC +/- 5 %, <= 10 mA for overload and short-circuit protection Internal supply, 24 V DC, voltage limits 21...27 V, <= 200 mA for overload and short-circuit protection
Analogue input number	2
Analogue input type	A11-/A11+ bipolar differential voltage +/- 10 V DC, input voltage 24 V max, resolution 11 bits + sign A12 software-configurable current 0...20 mA, impedance 242 Ohm, resolution 11 bits A12 software-configurable voltage 0...10 V DC, input voltage 24 V max, impedance 30000 Ohm, resolution 11 bits
Input sampling time	A11-/A11+ 2 ms, +/- 0.5 ms for analog input(s) A12 2 ms, +/- 0.5 ms for analog input(s) L11...L15 2 ms, +/- 0.5 ms for discrete input(s) L16 (if configured as logic input) 2 ms, +/- 0.5 ms for discrete input(s)
Response time	<= 100 ms in STO (Safe Torque Off) AO1 2 ms, tolerance +/- 0.5 ms for analog output(s) R1A, R1B, R1C 7 ms, tolerance +/- 0.5 ms for discrete output(s) R2A, R2B 7 ms, tolerance +/- 0.5 ms for discrete output(s)
Absolute accuracy precision	A11-/A11+ +/- 0.6 % for a temperature variation 60 °C A12 +/- 0.6 % for a temperature variation 60 °C AO1 +/- 1 % for a temperature variation 60 °C
Linearity error	A11-/A11+, A12 +/- 0.15 % of maximum value AO1 +/- 0.2 %
Analogue output number	1
Analogue output type	AO1 software-configurable current 0...20 mA, impedance 500 Ohm, resolution 10 bits AO1 software-configurable logic output 10 V <= 20 mA AO1 software-configurable voltage 0...10 V DC, impedance 470 Ohm, resolution 10 bits
Discrete output number	2
Discrete output type	R1A, R1B, R1C configurable relay logic NO/NC, electrical durability 100000 cycles R2A, R2B configurable relay logic NO, electrical durability 100000 cycles
Minimum switching current	Configurable relay logic 3 mA at 24 V DC
Maximum switching current	R1, R2 on resistive load, 5 A at 250 V AC, cos phi = 1, R1, R2 on resistive load, 5 A at 30 V DC, cos phi = 1,

R1, R2 on inductive load, 2 A at 250 V AC, cos phi = 0.4,
R1, R2 on inductive load, 2 A at 30 V DC, cos phi = 0.4,

Discrete input number	7
Discrete input type	LI6 : switch-configurable 24 V DC with level 1 PLC, impedance: 3500 Ohm PWR : safety input 24 V DC, impedance: 1500 Ohm conforming to ISO 13849-1 level d LI1...LI5 : programmable 24 V DC with level 1 PLC, impedance: 3500 Ohm LI6 : switch-configurable PTC probe 0...6, impedance: 1500 Ohm
Discrete input logic	LI1...LI5 positive logic (source), < 5 V (state 0), > 11 V (state 0) LI1...LI5 negative logic (sink), > 16 V (state 0), < 10 V (state 0) LI6 (if configured as logic input) positive logic (source), < 5 V (state 0), > 11 V (state 0) LI6 (if configured as logic input) negative logic (sink), > 16 V (state 0), < 10 V (state 0)
Acceleration and deceleration ramps	Automatic adaptation of ramp if braking capacity exceeded, by using resistor Linear adjustable separately from 0.01 to 9000 s S, U or customized
Braking to standstill	By DC injection
Protection type	Drive against exceeding limit speed Drive against input phase loss Drive break on the control circuit Drive input phase breaks Drive line supply overvoltage Drive line supply undervoltage Drive overcurrent between output phases and earth Drive overheating protection Drive overvoltages on the DC bus Drive short-circuit between motor phases Drive thermal protection Motor motor phase break Motor power removal Motor thermal protection
Insulation resistance	> 1 mOhm at 500 V DC for 1 minute to earth
Frequency resolution	Analog input 0.024/50 Hz Display unit 0.1 Hz
Communication port protocol	CANopen Modbus
Connector type	1 RJ45 for Modbus on front face 1 RJ45 for Modbus on terminal Male SUB-D 9 on RJ45 for CANopen
Physical interface	2-wire RS 485 for Modbus
Transmission frame	RTU for Modbus
Transmission rate	20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps for CANopen 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps for Modbus on terminal 9600 bps, 19200 bps for Modbus on front face
Data format	8 bits, 1 stop, even parity for Modbus on front face 8 bits, odd even or no configurable parity for Modbus on terminal
Number of addresses	1...247 for Modbus 1...127 for CANopen
Method of access	Slave for CANopen
Marking	CE
Operating position	Vertical +/- 10 degree
Height	420 mm
Depth	236 mm
Width	230 mm
Product weight	21 kg
Option card	CC-Link communication card Controller inside programmable card DeviceNet communication card Ethernet/IP communication card Fipio communication card I/O extension card Interbus-S communication card Interface card for encoder Modbus Plus communication card Modbus TCP communication card Modbus/Uni-Telway communication card Overhead crane card Profibus DP communication card

Environment

Noise level	59.9 dB conforming to 86/188/EEC
Dielectric strength	3535 V DC between earth and power terminals 5092 V DC between control and power terminals
Electromagnetic compatibility	Conducted radio-frequency immunity test conforming to IEC 61000-4-6 level 3 Electrical fast transient/burst immunity test conforming to IEC 61000-4-4 level 4 Electrostatic discharge immunity test conforming to IEC 61000-4-2 level 3 Radiated radio-frequency electromagnetic field immunity test conforming to IEC 61000-4-3 level 3 Voltage dips and interruptions immunity test conforming to IEC 61000-4-11 1.2/50 μ s - 8/20 μ s surge immunity test conforming to IEC 61000-4-5 level 3
Standards	EN 55011 class A group 2 EN 61800-3 environments 1 category C3 EN 61800-3 environments 2 category C3 EN/IEC 61800-3 EN/IEC 61800-5-1 IEC 60721-3-3 class 3C1 IEC 60721-3-3 class 3S2 UL Type 1
Product certifications	CSA C-Tick NOM 117 UL
Pollution degree	2 conforming to EN/IEC 61800-5-1 3 conforming to UL 840
IP degree of protection	IP20 on upper part without blanking plate on cover conforming to EN/IEC 60529 IP20 on upper part without blanking plate on cover conforming to EN/IEC 61800-5-1 IP21 conforming to EN/IEC 60529 IP21 conforming to EN/IEC 61800-5-1 IP41 on upper part conforming to EN/IEC 60529 IP41 on upper part conforming to EN/IEC 61800-5-1 IP54 on lower part conforming to EN/IEC 60529 IP54 on lower part conforming to EN/IEC 61800-5-1
Vibration resistance	1.5 mm peak to peak (f = 3...13 Hz) conforming to EN/IEC 60068-2-6 1 gn (f = 13...200 Hz) conforming to EN/IEC 60068-2-6
Shock resistance	15 gn for 11 ms conforming to EN/IEC 60068-2-27
Relative humidity	5...95 % without condensation conforming to IEC 60068-2-3 5...95 % without dripping water conforming to IEC 60068-2-3
Ambient air temperature for operation	-10...50 °C without derating
Ambient air temperature for storage	-25...70 °C
Operating altitude	\leq 1000 m without derating 1000...3000 m with current derating 1 % per 100 m