

# Product data sheet

Specifications



## enclosed variable speed drive ATV71 Plus - 160 kW - 690 V - IP54

ATV71EXC5C16Y

⚠ Discontinued on: Mar 12, 2021

⚠ To be end-of-service on: Dec 31, 2029

⚠ Discontinued - Service only

### Main

Range Of Product	Altivar 71 Plus
Product Or Component Type	Variable speed drive
Device Short Name	ATV71 Plus
Product Destination	Asynchronous motors Synchronous motors
Product Specific Application	Complex, high-power machines
Assembly Style	In floor-standing enclosure compact version
Product Composition	A wired ready-assembled Sarel Spacial 6000 enclosure Terminals/bars for motor connection ATV71HC16Y drive on heatsink An IP65 remote mounting kit for graphic display terminal A line choke A switch and fast-acting semi-conductor fuses
Emc Filter	Integrated
Network Number Of Phases	3 phases
Rated Supply Voltage	690 V +/- 10 %
Supply Voltage Limits	621...759 V
Supply Frequency	50...60 Hz +/- 5 %
Network Frequency	47.5...63 Hz
Motor Power Kw	160 kW at 690 V
Line Current	163 A for 690 V / 160 kW

### Complementary

Apparent Power	195 kVA for 690 V / 160 kW
Prospective Line Isc	100 kA with external fuses
Continuous Output Current	180 A at 2.5 kHz, 690 V / 160 kW
Maximum Transient Current	270 A for 60 s / 160 kW
Speed Drive Output Frequency	0...500 Hz
Nominal Switching Frequency	2.5 kHz
Switching Frequency	2.5...4.9 kHz with derating factor 2...4.9 kHz adjustable
Speed Range	1...100 in open-loop mode, without speed feedback
Speed Accuracy	+/- 0.01 % of nominal speed in closed-loop mode with encoder feedback 0.2 Tn to Tn +/- 10 % of nominal slip without speed feedback 0.2 Tn to Tn

Disclaimer: This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications

<b>Torque Accuracy</b>	+/- 15 % in open-loop mode, without speed feedback +/- 5 % in closed-loop mode with encoder feedback
<b>Transient Overtorque</b>	170 % of nominal motor torque +/- 10 % for 60 s 220 % of nominal motor torque +/- 10 % for 2 s
<b>Braking Torque</b>	<= 150 % with braking or hoist resistor 30 % without braking resistor
<b>Asynchronous Motor Control Profile</b>	Flux vector control without sensor, standard Voltage/frequency ratio, 5 points Flux vector control without sensor, 2 points Voltage/frequency ratio, 2 points Voltage/frequency ratio - Energy Saving, quadratic U/f Flux vector control with sensor, standard Flux vector control without sensor, ENA (energy Adaptation) system
<b>Synchronous Motor Control Profile</b>	Vector control without sensor, standard Vector control with sensor, standard
<b>Regulation Loop</b>	Adjustable PI regulator
<b>Motor Slip Compensation</b>	Not available in voltage/frequency ratio (2 or 5 points) Suppressable Adjustable Automatic whatever the load
<b>Overvoltage Category</b>	Class 3 conforming to EN 50178
<b>Local Signalling</b>	LCD display unit for operation function, status and configuration
<b>Output Voltage</b>	<= power supply voltage
<b>Isolation</b>	Electrical between power and control
<b>Type Of Cable For External Connection</b>	IEC cable at 40 °C, copper 70 °C / PVC
<b>Electrical Connection</b>	Terminal M10 - 2 x 150 mm <sup>2</sup> (U/T1, V/T2, W/T3) entry from the bottom Terminal - 2.5 mm <sup>2</sup> / AWG 14 (AI1-/AI1+, AI2, AO1, R1A, R1B, R1C, R2A, R2B, LI1...LI6, PWR) entry from the bottom Terminal M12 - 2 x 185 mm <sup>2</sup> (L1/R, L2/S, L3/T) entry from the bottom
<b>Motor Recommended Cable Cross Section</b>	3 x 95 mm <sup>2</sup>
<b>Short-Circuit Protection</b>	250 A fuse protection type gI - power supply upstream
<b>Supply</b>	External supply: 24 V DC (19...30 V), <1 A Internal supply for reference potentiometer: 10 V DC (10...11 V), <10 mA Internal supply: 24 V DC (21...27 V), <100 mA
<b>Analogue Input Number</b>	2
<b>Analogue Input Type</b>	AI2 software-configurable voltage: 0...10 V DC, 24 V max, impedance: 30000 Ohm, sampling time: 1.5...2.5 ms, resolution: 11 bits AI1-/AI1+ bipolar differential voltage: +/- 10 V DC, 24 V max, sampling time: 1.5...2.5 ms, resolution: 11 bits + sign AI2 software-configurable current: 0...20 mA/4...20 mA, impedance: 250 Ohm, sampling time: 1.5...2.5 ms, resolution: 11 bits
<b>Analogue Output Number</b>	1
<b>Analogue Output Type</b>	Software-configurable voltage: (AO1) 0...10 V DC - 470 Ohm - sampling time: 1.5...2.5 ms - resolution: 10 bits Software-configurable current: (AO1) 0...20 mA/4...20 mA - 500 Ohm - sampling time: 1.5...2.5 ms - resolution: 10 bits
<b>Discrete Output Number</b>	2
<b>Discrete Output Type</b>	Configurable relay logic: (R1A, R1B, R1C)NO/NC - 6.5...7.5 ms - 100000 cycles Configurable relay logic: (R2A, R2B)NO - 6.5...7.5 ms - 100000 cycles
<b>Minimum Switching Current</b>	3 mA at 24 V DC (configurable relay logic)
<b>Maximum Switching Current</b>	5 A at 250 V AC on resistive load - cos phi = 1 (R1, R2) 5 A at 30 V DC on resistive load - L/R = 0 ms (R1, R2) 2 A at 250 V AC on inductive load - cos phi = 0.4 (R1, R2) 2 A at 30 V DC on inductive load - L/R = 7 ms (R1, R2)
<b>Discrete Input Number</b>	7

<b>Discrete Input Type</b>	Programmable (LI1...LI5) at 24 V DC <= 30 V level 1 PLC 3.5 kOhm (duration=1.5...2.5 ms) Switch-configurable (LI6) at 24 V DC <= 30 V level 1 PLC 1.5 kOhm (duration=1.5...2.5 ms) Safety input (PWR) at 24 V DC <= 30 V 1.5 kOhm
<b>Discrete Input Logic</b>	Positive logic (source) (LI1...LI6), 0...5 V (state 0), 11...30 V (state 1) Negative logic (sink) (LI1...LI6), 16...30 V (state 0), 0...10 V (state 1) Positive logic (source) (PWR), 0...2 V (state 0), 17...30 V (state 1)
<b>Acceleration And Deceleration Ramps</b>	Linear adjustable separately from 0.01 to 9000 s S, U or customized Automatic adaptation of ramp if braking capacity exceeded, by using resistor
<b>Braking To Standstill</b>	By DC injection
<b>Protection Type</b>	Against exceeding limit speed: drive Against input phase loss: drive Break on the control circuit: drive Input phase breaks: drive Line supply overvoltage: drive Line supply undervoltage: drive Overcurrent between output phases and earth: drive Overheating protection: drive Overvoltages on the DC bus: drive Short-circuit between motor phases: drive Thermal protection: drive Input phase breaks: motor Power removal: motor Thermal protection: motor
<b>Dielectric Strength</b>	3110 V DC between earth and power terminals 5345 V DC between control and power terminals
<b>Insulation Resistance</b>	> 1 mOhm 500 V DC for 1 minute to earth
<b>Frequency Resolution</b>	Analog input: 0.024/50 Hz Display unit: 0.1 Hz
<b>Communication Port Protocol</b>	CANopen Modbus
<b>Connector Type</b>	1 RJ45 (on front face) for Modbus 1 RJ45 (on terminal) for Modbus Male SUB-D 9 on RJ45 for CANopen
<b>Physical Interface</b>	2-wire RS 485 for Modbus
<b>Transmission Frame</b>	RTU for Modbus
<b>Transmission Rate</b>	4800 bps, 9600 bps, 19200 bps, 38.4 Kbps for Modbus on terminal 9600 bps, 19200 bps for Modbus on front face 20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps for CANopen
<b>Data Format</b>	8 bits, 1 stop, even parity for Modbus on front face 8 bits, odd even or no configurable parity for Modbus on terminal
<b>Type Of Polarization</b>	No impedance for Modbus
<b>Number Of Addresses</b>	1...247 for CANopen 1...247 for Modbus
<b>Method Of Access</b>	Slave CANopen
<b>Option Card</b>	Communication card for CC-Link Communication card for DeviceNet Communication card for EtherNet/IP Communication card for Fipio Communication card for Interbus-S Communication card for Modbus Plus Communication card for Modbus/Uni-Telway Communication card for Profibus DP Communication card for Profibus DP V1 Communication card for Modbus TCP/IP Controller inside programmable card Basic I/O extension card Extended I/O extension card Encoder interface cards

Options For Enclosure Configuration	Safe standstill for power circuit
	PTC relay for power circuit
	Pt100 relay for power circuit
	Insulation monitoring for power circuit
	Design for IT networks for power circuit
	External 230 V supply terminals for power circuit
	Buffer voltage 24 V DC power supply for power circuit
	External 24 V DC supply terminals for power circuit
	Enclosure lighting for power circuit
	Key switch (local/remote) for power circuit
	Motor heating for power circuit
	External motor fan for power circuit
	Voltmeter for power circuit
	Door handle for main switch for power circuit
	Circuit breaker for power circuit
	Line contactor for power circuit
	Ammeter for power circuit
	Enclosure heating for power circuit
	Motor choke for power circuit
	Cable entry via the top for power circuit
	Enclosure plinth for power circuit
	Braking unit for power circuit
	Door handle for circuit breaker for power circuit
	Control terminals for control circuit
	Adaptor for 115 V logic inputs for control circuit
	Relay output C/O for control circuit
	Isolated amplifier for control circuit
Operating Position	Vertical +/- 10 degree
Colour Of Enclosure	Light grey (RAL 7035)
Height	2262 mm
Width	600 mm
Depth	642 mm
Net Weight	410 kg

## Environment

Electromagnetic Compatibility	1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5
	Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6
	Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4
	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2
	Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3
	Voltage dips and interruptions immunity test conforming to IEC 61000-4-11
Pollution Degree	3 conforming to EN/IEC 61800-5-1
Ip Degree Of Protection	IP54
Vibration Resistance	0.6 gn (f= 10...200 Hz) conforming to EN/IEC 60068-2-6
	1.5 mm (f= 3...10 Hz) conforming to EN/IEC 60068-2-6
	3M3 conforming to EN/IEC 60721-3-3
Shock Resistance	4 gn for 11 ms conforming to EN/IEC 60068-2-27
	3M2 conforming to EN/IEC 60721-3-3
Noise Level	65 dB conforming to 86/188/EEC
Environmental Characteristic	Without condensation: 3C2 conforming to IEC 60721-3-3
	Without condensation: 3K3 conforming to IEC 60721-3-3
	Without condensation: 3S2 conforming to IEC 60721-3-3
Relative Humidity	0...95 %
Ambient Air Temperature For Operation	0...40 °C (without derating)
	40...50 °C (with current derating of 0.6 % per °C)
Ambient Air Temperature For Storage	-25...70 °C
Volume Of Cooling Air	600 m3/h
Operating Altitude	<= 1000 m without derating
	1000...3000 m with current derating 1 % per 100 m

Standards	EN/IEC 61800-5-1
	EN 61800-3 environments 2 category C3
	EN/IEC 61800-3
	EN 61800-3 environments 1 category C3
	EN 55011 class A group 2
Product Certifications	GOST
	ATEX
Marking	CE

## Packing Units

Unit Type Of Package 1	PCE
Number Of Units In Package 1	1
Package 1 Height	216.0 cm
Package 1 Width	66.0 cm
Package 1 Length	61.6 cm
Package 1 Weight	410.0 kg

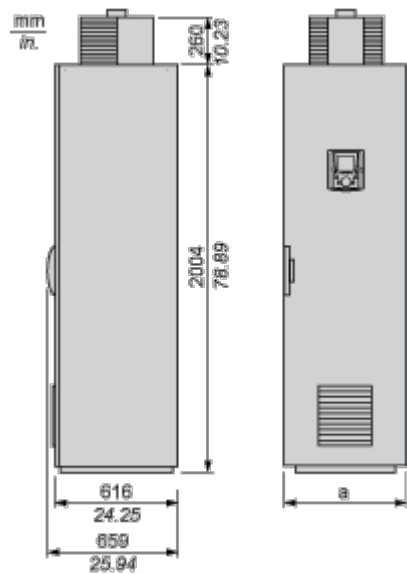
## Contractual warranty

Warranty	18 months
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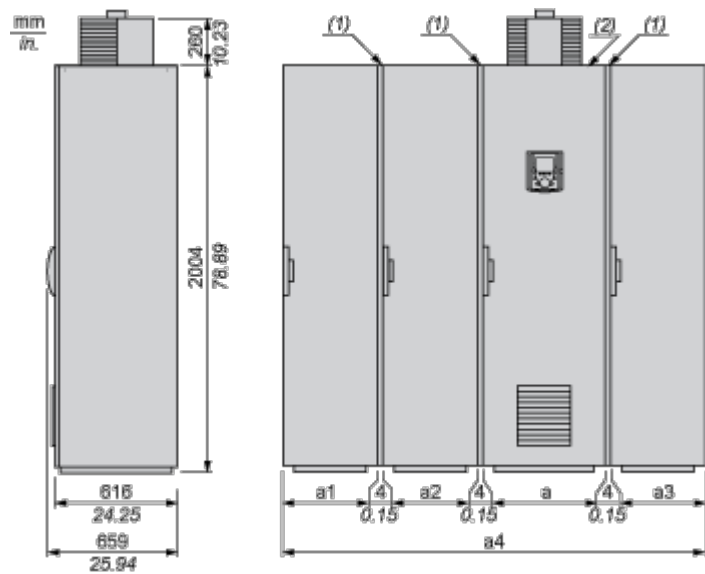
Dimensions Drawings

IP 54 Floor-Standing Enclosure Compact Version

Standard Compact Floor-Standing Enclosure



Standard Compact Floor-Standing Enclosure + Additional Floor-Standing Enclosures, According to the Configuration



- (1) Seal. For each floor-standing enclosure added, allow a 4 mm/0.15 in. space for the seal.
- (2) Standard IP 54 compact version floor-standing enclosure.

NOTE: The position of the enclosures must be complied with during installation. The number of additional enclosures can vary according to the chosen configuration.

Options	a	a1	a2	a3	a4
With or without common options or options dependent on the drive rating	616 mm/ 24.2 in.	–	–	–	616 mm/ 24.2 in.
Cable entry via the top option	608 mm/ 23.9 in.	–	408 mm/ 16 in.	–	1020 mm/ 40.1 in.
<p>(3) Except sinus filter option, which requires an additional enclosure. The sinus filter option is not compatible with the cable entry via the top option.</p> <p>(4) The cable entry via the top option is not compatible with the sinus filter option.</p>					

Connections and Schema

Floor-Standing Enclosure Compact Version

Wiring Diagram



- A1 Drive
- A2 Enclosure
- F1 Fast-acting semi-conductor fuse
- IL1 Line choke
- Q1 Switch
- (1) Fault relay contacts. For remote signalling of drive status.



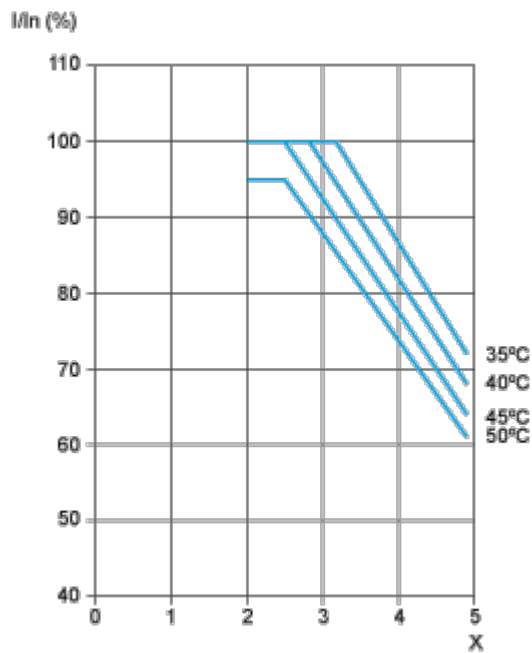
Performance Curves

Floor-Standing Enclosure Compact Version

Derating Curves

The derating curves for the drive nominal current (In) are dependent on the temperature and switching frequency. For intermediate temperatures, interpolate between 2 curves.

NOTE: The drive will reduce the switching frequency automatically in the event of excessive temperature rise.



X Switching frequency (kHz)

NOTE: The temperatures shown correspond to the temperature of the air entering the enclosure.