## Product data sheet

Specifications
(!) Discontinued - Service only

## enclosed variable speed drive ATV71 Plus - 1500 kW - 690V IP54

ATV71EXA5M15Y
(!) Discontinued on: Dec 31, 2023
(!) To be end-of-service on: Dec 31, 2031

Main

| Range Of Product | Altivar 71 Plus |
| :--- | :--- |
| Product Or Component Type | Variable speed drive |
| Device Short Name | ATV71 Plus |
| Product Destination | Asynchronous motors |
| Synchronous motors |  |
| Product Specific Application | Complex, high-power machines |
| Assembly Style | With integrated cooling circuit <br> In floor-standing enclosure with separate air flows |
| Product Composition | Integrated drive system ATV71EM15YE1 |
|  | A switch and fast-acting fuses |
| Terminals/bars for motor connection |  |
| Control transformer for 230 V |  |
| An IP65 remote mounting kit for graphic display terminal |  |
| A wired ready-assembled Sarel Spacial 6000 enclosure |  |
| Emc Filter | Integrated |
| Network Number Of Phases | 3 phases |
| Rated Supply Voltage | $690 \mathrm{~V} \mathrm{+/-10} \mathrm{\%}$ |
| Supply Voltage Limits | $621 \ldots 759 \mathrm{~V}$ |
| Supply Frequency | $50 \ldots 60 \mathrm{~Hz}+/-5 \%$ |
| Network Frequency | $47.5 \ldots 63 \mathrm{~Hz}$ |
| Motor Power Kw | $1500 \mathrm{~kW}, 3$ phases at 690 V |
| Line Current | 1514 A for $690 \mathrm{~V} / 1500 \mathrm{~kW}$ |

Complementary

| Apparent Power | 1809 kVA for $690 \mathrm{~V} / 1500 \mathrm{~kW}$ |
| :--- | :--- |
| Prospective Line Isc | 100 kA with external fuses |
| Continuous Output Current | 1580 A at $2.5 \mathrm{kHz}, 690 \mathrm{~V} / 1500 \mathrm{~kW}$ |
| Maximum Transient Current | 2370 A for $60 \mathrm{~s} / 1500 \mathrm{~kW}$ |
| Speed Drive Output Frequency | $0.1 \ldots 500 \mathrm{~Hz}$ |
| Nominal Switching Frequency | 2.5 kHz |
| Switching Frequency | $2 . . .4 .9 \mathrm{kHz}$ adjustable |
|  | $2.5 \ldots 4.9 \mathrm{kHz}$ with derating factor |


| Speed Range | 1... 100 for asynchronous motor in open-loop mode, without speed feedback <br> 1... 50 for synchronous motor in open-loop mode, without speed feedback <br> 1... 1000 for asynchronous motor in closed-loop mode with encoder feedback |
| :---: | :---: |
| Speed Accuracy | $+/-0.01 \%$ of nominal speed in closed-loop mode with encoder feedback 0.2 Tn to Tn <br> +/- $10 \%$ of nominal slip without speed feedback 0.2 Tn to Tn |
| Torque Accuracy | +/- $5 \%$ in closed-loop mode with encoder feedback <br> + +- $15 \%$ in open-loop mode, without speed feedback |
| Transient Overtorque | $170 \%$ of nominal motor torque for 60 s $220 \%$ of nominal motor torque for 2 s |
| Braking Torque | 30 \% without braking resistor <= $150 \%$ with braking or hoist resistor |
| Asynchronous Motor Control Profile | Flux vector control without sensor, standard <br> Flux vector control without sensor, ENA (energy Adaptation) system <br> Voltage/frequency ratio, 2 points <br> Voltage/frequency ratio, 5 points <br> Voltage/frequency ratio - Energy Saving, quadratic U/f <br> Flux vector control without sensor, 2 points <br> Flux vector control with sensor, standard |
| Synchronous Motor Control Profile | Vector control with sensor, standard Vector control without sensor, standard |
| Regulation Loop | Adjustable PI regulator |
| Motor Slip Compensation | Suppressable <br> Adjustable <br> Automatic whatever the load <br> Not available in voltage/frequency ratio (2 or 5 points) |
| Overvoltage Category | Class 3 conforming to EN 50178 |
| Local Signalling | LCD display unit for operation function, status and configuration - mounted in the front door |
| Output Voltage | <= supply voltage |
| Isolation | Electrical between power and control |
| Type Of Cable For External Connection | IEC cable at $40^{\circ} \mathrm{C}$, copper $70^{\circ} \mathrm{C} / \mathrm{PVC}$ <br> UL 508 cable at $40^{\circ} \mathrm{C}$, copper $75^{\circ} \mathrm{C} / \mathrm{PVC}$ |
| Electrical Connection | Terminal - $2.5 \mathrm{~mm}^{2}$ / AWG 14 (R1A, R1B, R1C, R2A, R2B) bottom entry Screw clamp terminals - $1.5 \mathrm{~mm}^{2}$ (Al1-/AI1+, Al2, AO1, LI1...LI6, PWR) bottom entry <br> Bar M12-16 $\times 240 \mathrm{~mm}^{2}$ (L1/R, L2/S, L3/T) bottom entry at 6 -pulse operation <br> Bar M12-8 $\times 240 \mathrm{~mm}^{2}$ (L1/R, L2/S, L3/T) bottom entry at 12-pulse operation <br> Bar M12-24 x $240 \mathrm{~mm}^{2}$ (U/T1, V/T2, W/T3) bottom entry |
| Motor Recommanded Cable Cross Section | $\begin{aligned} & 6(3 \times 240) \mathrm{mm}^{2} \\ & 7(3 \times 185) \mathrm{mm}^{2} \end{aligned}$ |
| Short-Circuit Protection | 2500 A fuse protection type gl - power supply upstream - at 6-pulse operation 1250 A fuse protection type gl - power supply upstream - at 12-pulse operation |
| Supply | External supply: 24 V DC ( $19 \ldots . .30 \mathrm{~V}$ ), $<1 \mathrm{~A}$ Internal supply for reference potentiometer: 10 V DC ( $10 \ldots 11 \mathrm{~V}$ ), < 10 mA Internal supply: 24 V DC ( $21 \ldots 27 \mathrm{~V}$ ), $<100 \mathrm{~mA}$ |
| Analogue Input Number | 2 |
| Analogue Input Type | Al2 software-configurable voltage: $0 . .10 \mathrm{~V}$ DC, 24 V max, impedance: 30000 Ohm, sampling time: $1.5 \ldots 2.5 \mathrm{~ms}$, resolution: 11 bits <br> Al1-/Al1+ bipolar differential voltage: +/- 10 V DC, 24 V max, sampling time: $1.5 \ldots . .2 .5$ ms , resolution: 11 bits + sign <br> Al2 software-configurable current: $0 \ldots 20 \mathrm{~mA} / 4 \ldots 20 \mathrm{~mA}$, impedance: 250 Ohm, sampling time: $1.5 \ldots 2.5 \mathrm{~ms}$, resolution: 11 bits |
| Analogue Output Number | 1 |
| Analogue Output Type | Software-configurable voltage: (AO1) $0 . . .10 \mathrm{~V}$ DC - 470 Ohm - sampling time: $1.5 \ldots$ 2.5 ms - resolution: 10 bits <br> Software-configurable current: (AO1) $0 . . .20 \mathrm{~mA} / 4 \ldots 20 \mathrm{~mA}$ - 500 Ohm - sampling time: 1.5 ... 2.5 ms - resolution: 10 bits |
| Discrete Output Number | 2 |


| Discrete Output Type | Configurable relay logic: (R1A, R1B, R1C)NO/NC - $6.5 \ldots 7.5 \mathrm{~ms}$ - 100000 cycles Configurable relay logic: (R2A, R2B)NO - 6.5... $7.5 \mathrm{~ms}-100000$ cycles |
| :---: | :---: |
| Minimum Switching Current | 3 mA at 24 V DC (configurable relay logic) |
| Maximum Switching Current | 5 A at 250 V AC on resistive load $-\cos$ phi $=1(\mathrm{R} 1, \mathrm{R} 2)$ 5 A at 30 V DC on resistive load $-\mathrm{L} / \mathrm{R}=0 \mathrm{~ms}$ (R1, R2) 2 A at 250 V AC on inductive load $-\cos$ phi $=0.4$ (R1, R2) 2 A at 30 V DC on inductive load $-\mathrm{L} / \mathrm{R}=7 \mathrm{~ms}$ |
| Discrete Input Number | 7 |
| Discrete Input Type | Programmable (LI1...LI5) at 24 V DC <= 30 V level 1 PLC 3.5 kOhm (duration=1.5... 2.5 ms ) <br> Switch-configurable (LI6) at 24 V DC $<=30 \mathrm{~V}$ level 1 PLC 1.5 kOhm (duration=1.5... 2.5 ms ) <br> Safety input (PWR) at 24 V DC <= 30 V 1.5 kOhm |
| Discrete Input Logic | Positive logic (source) (LI1...LI5), $0 \ldots 5 \mathrm{~V}$ (state 0 ), $11 \ldots 30 \mathrm{~V}$ (state 1 ) Negative logic (sink) (LI1...LI5), 16... 30 V (state 0), $0 . . .10 \mathrm{~V}$ (state 1) Positive logic (source) (PWR), $0 . .2 \mathrm{~V}$ (state 0), 17... 30 V (state 1) |
| Acceleration And Deceleration Ramps | S, U or customized Linear adjustable separately from 0.01 to 9000 s |
| Braking To Standstill | By DC injection |
| Protection Type | Overheating protection: drive <br> Thermal protection: drive <br> Short-circuit between motor phases: drive <br> Input phase breaks: drive <br> Overcurrent between output phases and earth: drive <br> Overvoltages on the DC bus: drive <br> Break on the control circuit: drive <br> Against exceeding limit speed: drive <br> Line supply undervoltage: drive <br> Line supply overvoltage: drive <br> Against input phase loss: drive <br> Thermal protection: motor <br> Motor phase break: motor <br> Power removal: motor |
| Dielectric Strength | 3535 V DC between earth and power terminals 5092 V DC between control and power terminals |
| Insulation Resistance | > 1 mOhm 500 V DC for 1 minute to earth |
| Frequency Resolution | Display unit: 0.1 Hz <br> Analog input: $0.024 / 50 \mathrm{~Hz}$ |
| Communication Port Protocol | CANopen Modbus |
| Connector Type | 1 RJ45 (on front face) for Modbus 1 RJ45 (on terminal) for Modbus Male SUB-D 9 on RJ45 for CANopen |
| Physical Interface | 2-wire RS 485 for Modbus |
| Transmission Frame | RTU for Modbus |
| Transmission Rate | 9600 bps, 19200 bps for Modbus on front face $4800 \mathrm{bps}, 9600 \mathrm{bps}, 19200 \mathrm{bps}, 38.4 \mathrm{Kbps}$ for Modbus on terminal $20 \mathrm{kbps}, 50 \mathrm{kbps}, 125 \mathrm{kbps}, 250 \mathrm{kbps}, 500 \mathrm{kbps}, 1 \mathrm{Mbps}$ for CANopen |
| Data Format | 8 bits, 1 stop, even parity for Modbus on front face <br> 8 bits, odd even or no configurable parity for Modbus on terminal |
| Type Of Polarization | No impedance for Modbus |
| Number Of Addresses | 1... 247 for Modbus <br> 1... 127 for CANopen |
| Method Of Access | Slave CANopen |


| Option Card | Communication card for Modbus TCP/IP <br> Communication card for Fipio <br> Communication card for Modbus/Uni-Telway <br> Communication card for Modbus Plus <br> Communication card for EtherNet/IP <br> Communication card for DeviceNet <br> Communication card for Profibus DP <br> Communication card for Profibus DP V1 <br> Communication card for Interbus-S <br> Communication card for CC-Link <br> Basic I/O extension card <br> Extended I/O extension card <br> Controller inside programmable card <br> Encoder interface cards |
| :---: | :---: |
| Options For Enclosure Configuration | Safe standstill for power circuit <br> PTC relay for power circuit Pt100 relay for power circuit Insulation monitoring for power circuit <br> Design for IT networks for power circuit <br> External 230 V supply terminals for power circuit <br> Buffer voltage 24 V DC power supply for power circuit <br> External 24 V DC supply terminals for power circuit <br> Enclosure lighting for power circuit <br> Key switch (local/remote) for power circuit <br> Motor heating for power circuit <br> External motor fan for power circuit <br> Voltmeter for power circuit <br> Door handle for main switch for power circuit <br> Circuit breaker for power circuit <br> Line contactor for power circuit <br> 12-pulse supply for power circuit <br> Line reactor for power circuit <br> Ammeter for power circuit <br> Enclosure heating for power circuit <br> Motor choke for power circuit <br> Cable entry via the top for power circuit <br> Enclosure plinth for power circuit <br> Door handle for circuit breaker for power circuit <br> Control terminals for control circuit <br> Adaptor for 115 V logic inputs for control circuit <br> Relay output C/O for control circuit <br> Isolated amplifier for control circuit |
| Operating Position | Vertical +/-10 degree |
| Colour Of Enclosure | Light grey (RAL 7035) |
| Colour Of Base Of Enclosure | Dark grey (RAL 7022) |
| Height | 2009 mm |
| Width | 3400 mm |
| Depth | 642 mm |
| Net Weight | 1925 kg |
| Environment |  |
| Electromagnetic Compatibility | Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 <br> Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 $1.2 / 50 \mu \mathrm{~s}-8 / 20 \mu \mathrm{~s}$ surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 Voltage dips and interruptions immunity test conforming to IEC 61000-4-11 |
| Pollution Degree | 3 conforming to EN/IEC 61800-5-1 |
| Ip Degree Of Protection | IP54 |
| Vibration Resistance | 1.5 mm peak to peak (f=3...10 Hz) conforming to EN/IEC 60068-2-6 0.6 gn ( $\mathrm{f}=10 \ldots 200 \mathrm{~Hz}$ ) conforming to EN/IEC 60068-2-6 3M3 conforming to EN/IEC 60721-3-3 |
| Shock Resistance | 4 gn for 11 ms conforming to EN/IEC 60068-2-27 3M2 conforming to EN/IEC 60721-3-3 |


| Noise Level | 79 dB conforming to 86/188/EEC |
| :---: | :---: |
| Environmental Characteristic | Without condensation: 3C2 conforming to IEC 60721-3-3 Without condensation: 3 S2 conforming to IEC 60721-3-3 Without condensation: 3K3 conforming to IEC 60721-3-3 |
| Relative Humidity | 0... $95 \%$ |
| Ambient Air Temperature For Operation | $0 \ldots 40^{\circ} \mathrm{C}$ (without derating) $40 \ldots 50^{\circ} \mathrm{C}$ (with current derating of $1.2 \%$ per ${ }^{\circ} \mathrm{C}$ ) |
| Ambient Air Temperature For Storage | $-25 \ldots 70^{\circ} \mathrm{C}$ |
| Volume Of Cooling Air | $11000 \mathrm{~m} 3 / \mathrm{h}$ |
| Operating Altitude | <= 1000 m without derating $1000 \ldots 3000 \mathrm{~m}$ with current derating $1 \%$ per 100 m |
| Standards | EN 61800-3 environments 2 category C3 <br> EN 55011 class A group 2 <br> EN/IEC 61800-3 <br> EN 61800-3 environments 1 category C3 <br> EN/IEC 61800-5-1 |
| Product Certifications | $\begin{aligned} & \text { ATEX } \\ & \text { GOST } \end{aligned}$ |
| Marking | CE |

## Packing Units

| Unit Type Of Package 1 | PCE |
| :--- | :--- |
| Number Of Units In Package 1 | 1 |
| Package 1 Height | 200.0 cm |
| Package 1 Width | 66.0 cm |
| Package 1 Length | 344.0 cm |
| Package 1 Weight | 1920.0 kg |

Contractual warranty

Warranty 18 months

Dimensions Drawings

IP 23 Floor-Standing Enclosure with Separate Air Flows

Dimensions


NOTE: For each floor-standing enclosure added, allow a $4 \mathrm{~mm} / 0.15 \mathrm{in}$. space for the seal.

Connections and Schema

Floor-Standing Enclosure with Separate Air Flows

Standard 6-pulse Design


A1 Drive
A2 Enclosure
F1 Fuses
IL1 Optional line choke
KM1 Optional line contactor

M Motor
Q1 Switch
(1) Filter
(2) Control
(3) Relay control
(4) Reference potentiometer
(5) PLC
(6) Optional motor choke

Optional 12-pulse Design


A1 Drive
A2 Enclosure
F1 Fuses
IL1 Optional line choke
KM1 Optional line contactor
M Motor
Q1 Switch
(1) Filter
(2) Control
(3) Relay control
(4) Reference potentiometer
(5) PLC
(6) Optional motor choke

Performance Curves

## IP 23 Floor-Standing Enclosure with Separate Air Flows

## Derating Curves

The derating curves for the drive nominal current (In) are dependent on the temperature and switching frequency. For intermediate temperatures, interpolate between 2 curves.

NOTE: The drive will reduce the switching frequency automatically in the event of excessive temperature rise.


X Switching frequency $(\mathrm{kHz})$

NOTE: The temperatures shown correspond to the temperature of the air entering the enclosure.

