## Product data sheet

Specifications


## variable speed drive ATV11 0.75 kW - 230V 1-phase supply IP20

ATV11HU18M2ETQ
(!) Discontinued on: Dec 31, 2010
(!) End-of-service on: Dec 31, 2012

## Main

| Range Of Product | Altivar 11 |
| :---: | :---: |
| Product Or Component Type | Variable speed drive |
| Product Specific Application | Simple machine |
| Component Name | ATV11 |
| Application Market | European |
| Assembly Style | With heat sink |
| Emc Filter | Integrated |
| Built-In Fan | Without |
| Network Number Of Phases | 1 phase |
| [Us] Rated Supply Voltage | 200... 240 V-15... 10 \% |
| Supply Frequency | $50 \ldots 60 \mathrm{~Hz}-5 . . .5$ \% |
| Motor Power Kw | 0.75 kW |
| Line Current | 8.6 A at $230 \mathrm{~V}, \mathrm{Isc}=1 \mathrm{kA}$ |
| Nominal Output Current | 3.6 A 230 V motor 4 kHz |
| Maximum Transient Current | 5.4 A for 60 s |
| Power Dissipation In W | 37 W at nominal load |
| Switching Frequency | 2... 12 kHz adjustable <br> $4 . . .12 \mathrm{kHz}$ with derating factor |
| Braking Torque | $150 \%$ of nominal motor torque with braking resistor at high inertia $20 \%$ of nominal motor torque without braking resistor at no load $80 \%$ of nominal motor torque with braking resistor at no load |
| Asynchronous Motor Control Profile | Sensorless flux vector control with PWM type motor control signal |
| Electrical Connection | Terminal, clamping capacity: $1.5 \mathrm{~mm}^{2}$, AWG 14 (AI1, RA-RC, LI1...LI4, DO) Terminal, clamping capacity: $4 \mathrm{~mm}^{2}$, AWG 10 (L1, L2, L3, U, V, W, PA, PC) |
| Supply | Internal supply for logic inputs: $15 \mathrm{~V}(+/-15 \%) 100 \mathrm{~A}$, protection type: overload and short-circuit protection <br> Internal supply for reference potentiometer ( 2.2 to 10 kOhm ): 5...5.25 VDC 10 A , protection type: overload and short-circuit protection |
| Analogue Input Type | Configurable current Al1 4... 20 mA 250 Ohm without adding resistor Configurable voltage Al1 $0 . . .5 \mathrm{~V} 40000$ Ohm only with internal supply Configurable current Al1 $0 \ldots . .20 \mathrm{~mA} 250 \mathrm{Ohm}$ Configurable voltage Al1 $0 . . .10 \mathrm{~V} 40000 \mathrm{Ohm}$ |
| Sampling Duration | Al1: 20 ms analog <br> LI1...LI4: 20 ms discrete |


| Response Time | 20 ms DO |
| :---: | :---: |
| Linearity Error | DO: +/- $1 \%$ for output AI: +/- 5 \% for input |
| Discrete Input Type | Assignable LI1 forward 5000 Ohm 15 V 24 V <br> Assignable LI2 reverse 5000 Ohm 15 V 24 V <br> Assignable LI3/LI4 4 preset speeds 5000 Ohm 15 V 24 V |
| Discrete Input Logic | Positive logic (source) (LI1 ...LI4), < 5 V (state 0 ), > 11 V (state 1) Negative (LI1...LI4), > 11 V (state 0), < 5 V (state 1) |
| Discrete Output Type | Assignable as external voltage DO 30 V max, 30 mA <br> Assignable as open collector logic output DO 100 Ohm, 50 mA max Factory set as PWM open collector output DO at 2 kHz 10 mA max Protected relay logic RA-RC 1 NO Assignable as internal voltage DO |
| Minimum Switching Current | RA-RC 10 mA at 24 V DC |
| Maximum Switching Current | 2 A 250 V AC inductive cos phi $=0.47 \mathrm{~ms}$ RA-RC <br> 2 A 30 V DC inductive cos phi $=0.47 \mathrm{~ms}$ RA-RC <br> 5 A 250 V AC resistive cos phi $=10 \mathrm{~ms}$ RA-RC <br> 5 A 30 V DC resistive cos phi $=10 \mathrm{~ms}$ RA-RC |
| Protection Type | Line supply overvoltage: drive <br> Line supply undervoltage: drive <br> Overheating protection: drive <br> Short-circuit between motor phases: drive <br> Thermal protection: motor <br> Overcurrent between output phases and earth: drive |
| Frequency Resolution | Display unit: 0.1 Hz Analog input: converter A/D, 10 bits |
| Electromagnetic Compatibility | $1.2 / 50 \mu \mathrm{~s}-8 / 20 \mu \mathrm{~s}$ surge immunity test level 3 conforming to EN/IEC 61000-4-5 Electrical fast transient/burst immunity test level 4 conforming to EN/IEC 61000-4-4 Electrostatic discharge immunity test level 3 conforming to EN/IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to EN/IEC 61000-4-3 |
| Maximum Motor Cable Length | 10 m without additional EMC filter from 2 to 16 kHz conforming to EN 55011 class A group 1 <br> 10 m without additional EMC filter from 2 to 16 kHz conforming to EN 55022 class A group 1 <br> 20 m with additional EMC filter from 2 to 16 kHz conforming to EN 55011 class B <br> 5 m without additional EMC filter from 2 to 12 kHz conforming to EN 55011 class B <br> 5 m without additional EMC filter from 2 to 12 kHz conforming to EN 55022 class B 50 m with additional EMC filter from 2 to 16 kHz conforming to EN 55011 class A group 1 |
| Vibration Resistance | $1 \mathrm{gn}(\mathrm{f}=13 \ldots 200 \mathrm{~Hz}$ ) conforming to EN/IEC 60068-2-6 1.5 mm peak to peak ( $\mathrm{f}=3 \ldots . .13 \mathrm{~Hz}$ ) conforming to EN/IEC 60068-2-6 |
| Shock Resistance | 15 gn for 11 ms conforming to EN/IEC 60068-2-27 |
| Relative Humidity | 5... 93 \% without condensation conforming to IEC 60068-2-3 <br> $5 . .93 \%$ without dripping water conforming to IEC 60068-2-3 |
| Ambient Air Temperature For Operation | $-10 . . .40^{\circ} \mathrm{C}$ without derating <br> $40 . . .50^{\circ} \mathrm{C}$ by removing the protective cover from the top of the drive $50 \ldots 60^{\circ} \mathrm{C}$ by removing the protective cover from the top of the drive with current derating of $2.2 \%$ per ${ }^{\circ} \mathrm{C}$ |
| Operating Altitude | $\begin{aligned} & \text { <= } 1000 \mathrm{~m} \text { without derating } \\ & >1000 \mathrm{~m} \text { with current derating } 1 \% \text { per } 100 \mathrm{~m} \end{aligned}$ |
| Complementary |  |
| Product Destination | Asynchronous motors |
| Supply Voltage Limits | 170... 264 V |
| Network Frequency Limits | $47.5 \ldots 63 \mathrm{~Hz}$ |
| Speed Drive Output Frequency | $0 . . .200 \mathrm{~Hz}$ |
| Nominal Switching Frequency | 4 kHz |


| Speed Range | $1 \ldots 20$ |
| :--- | :--- |
| Transient Overtorque | $150 \ldots 170 \%$ of nominal motor torque |
| Regulation Loop | Possible correction for machines with high resistive torque/inertia/fast cycles <br> Factory-set with the speed loop stability and gain <br> Adjustable frequency |
| Motor Slip Compensation | Preset in factory <br> Adjustable |
| Prospective Line Isc | 1 kA |
| Output Voltage | $<=$ power supply voltage |
| Insulation | 1 |
| Analogue Input Number | 4 |
| Discrete Input Number between power and control |  |
| Discrete Output Number | 2 |
| Acceleration And Deceleration | Linear from 0 to 99.9 s |
| Ramps | By DC injection |
| Braking To Standstill | $>500 \mathrm{MOhm}$ |
| Insulation Resistance | CE |
| Marking | Vertical $+/-10$ degree |
| Operating Position | $142 \times 72 \times 145 \mathrm{~mm}$ |
| Outer Dimension | 1.1 kg |
| Net Weight |  |

Environment

| Standards | EN 50178 |
| :--- | :--- |
| Product Certifications | N998 |
|  | C-Tick |
|  | CSA |
| UL Degree Of Protection | IP 20 |
| Ambient Air Temperature For <br> Storage | $-25 \ldots 65^{\circ} \mathrm{C}$ |

